



Distributed Schur Complement Solvers for Real and Complex Block-Structured CFD Problems

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German Aerospace Center (DLR)

Simulation- and Software Technology

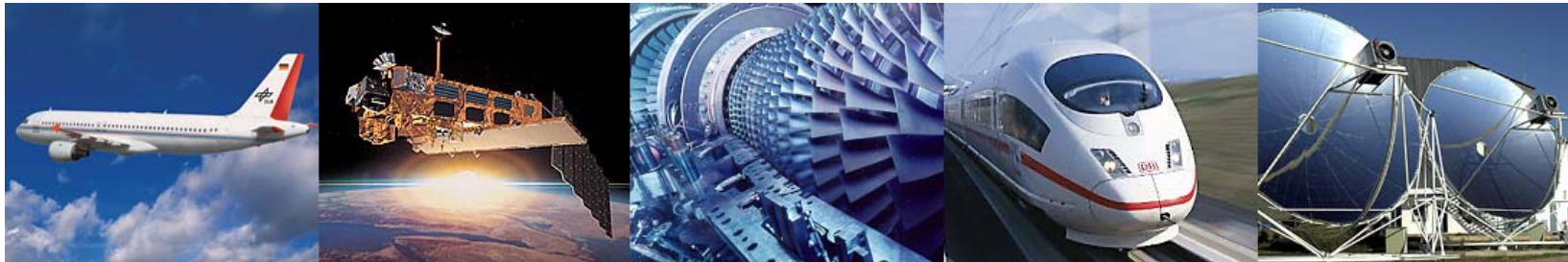
Distributed Systems and Component Software

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DLR **German Aerospace Center**



- Research Institution
- Space Agency
- Project Management Agency

DLR





Locations and employees

Germany: 6000 employees across 29 research institutes and facilities at

■ 13 sites.

Offices in **Brussels**,
Paris and **Washington**.

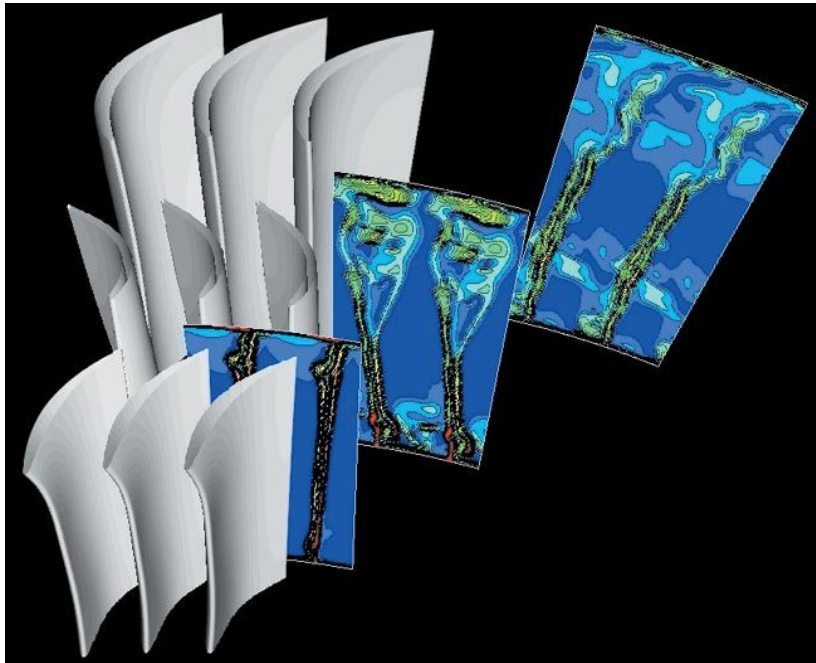
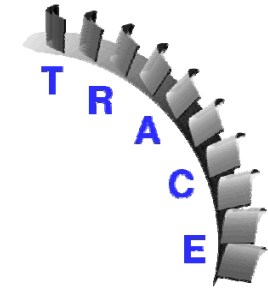




Survey

- Motivation
- The *Distributed Schur Complement* method (DSC)
- Complex and real problem formulation
- Experiments with TRACE matrices
- Conclusions

Parallel Simulation System TRACE



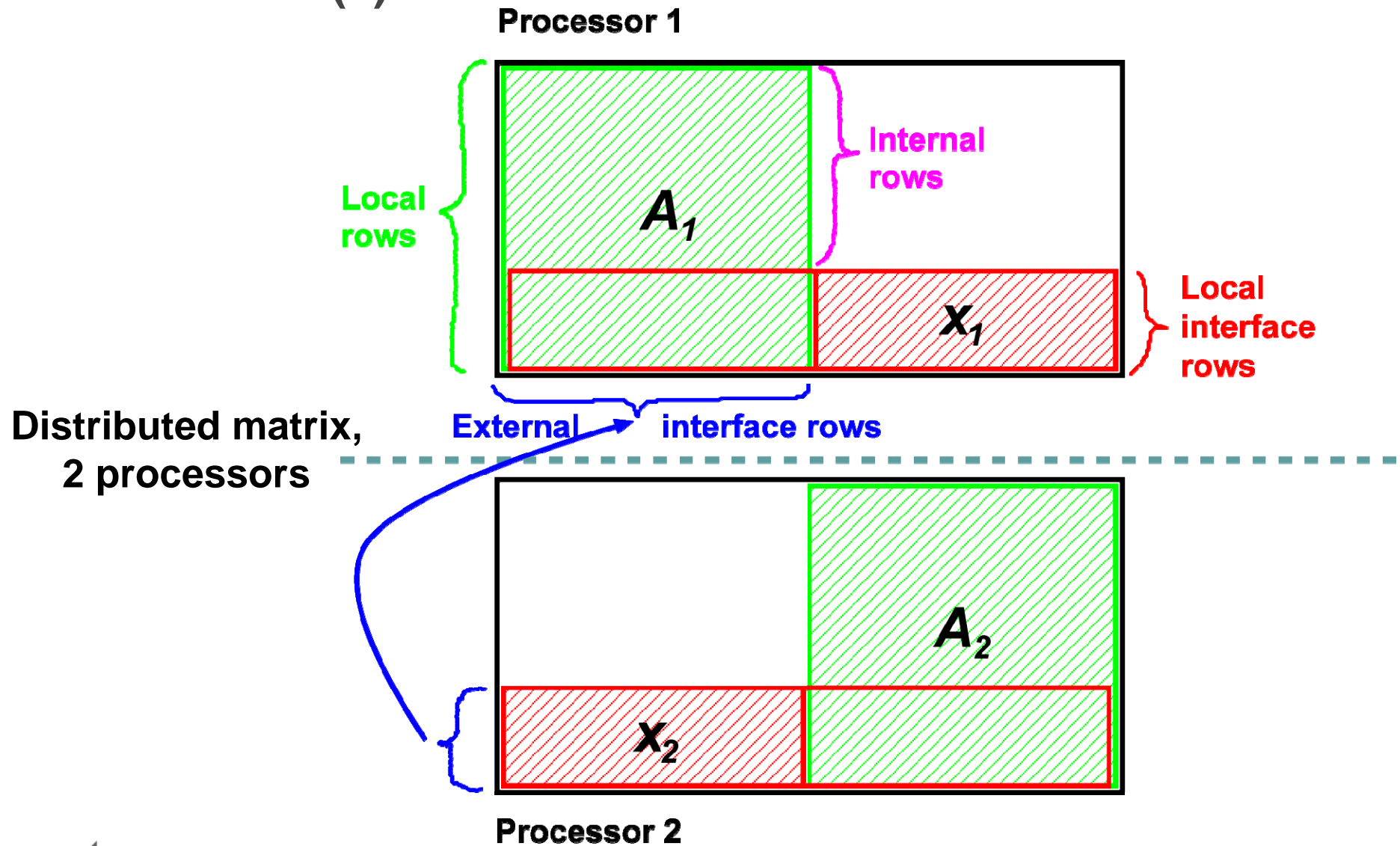
- TRACE: Turbo-machinery Research Aerodynamic Computational Environment
- Developed by the Institute for Propulsion Technology of the German Aerospace Center (DLR-AT)
- Calculates internal turbo-machinery flows
- Finite volume method with block-structured grids
- The linearized TRACE modules require the parallel, iterative solution of large, sparse non-symmetric systems of linear equations.



Preconditioners for TRACE: Background

- Modules linearTRACE or adjointTRACE $Ax = b$
 - A non-symmetric, complex or real, sparse
 - Parallel iterative solver: (F)GMRes with preconditioning $P^{-1}Ax = P^{-1}b$
 - Distinctly dominates the time behavior
 - Matrix-vector and vector-vector operations
 - **Preconditioning usually is the most time-consuming operation**
 - Crucial for scalability
 - Status: Block-local preconditioning
 - ILU, SSOR
 - **Scalability limited**
 - Goal: global, scalable preconditioner
 - **Experiments with Distributed Schur Complement (DSC) methods**

DSC Method (1)



DSC Method (2)

DSC Algorithm

Schematic view on
each processor

**BiCGstab or FGMRes iteration
for all local rows (unknowns)**

...

**BiCGstab iteration for the local
interface rows (unknowns)**

...

**Matrix-vector multiplication:
communication of external
interface unknowns**

...

...

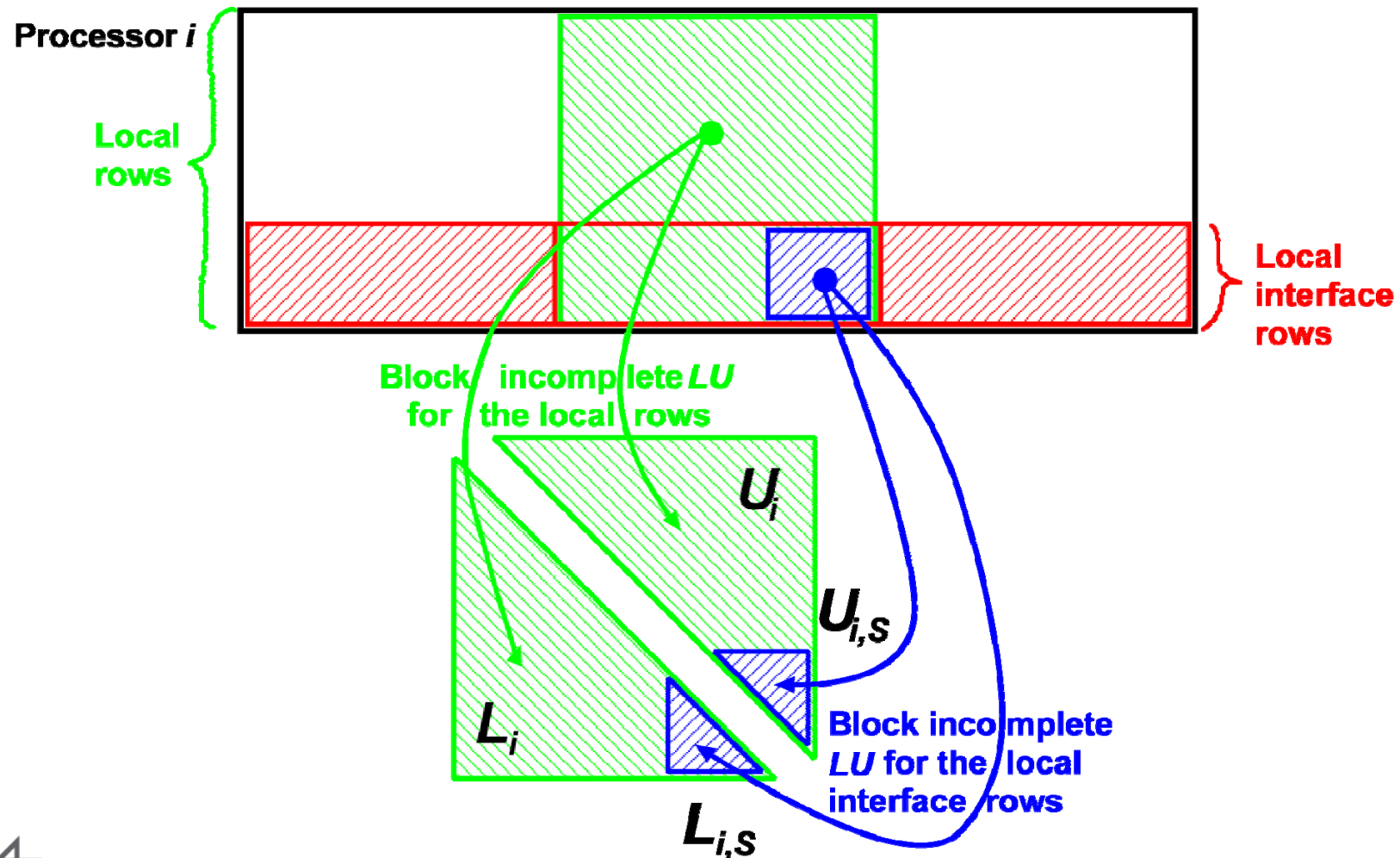
**Matrix-vector multiplication:
communication of external
interface unknowns**

...



DSC Method (3)

Preconditioning within the DSC algorithm

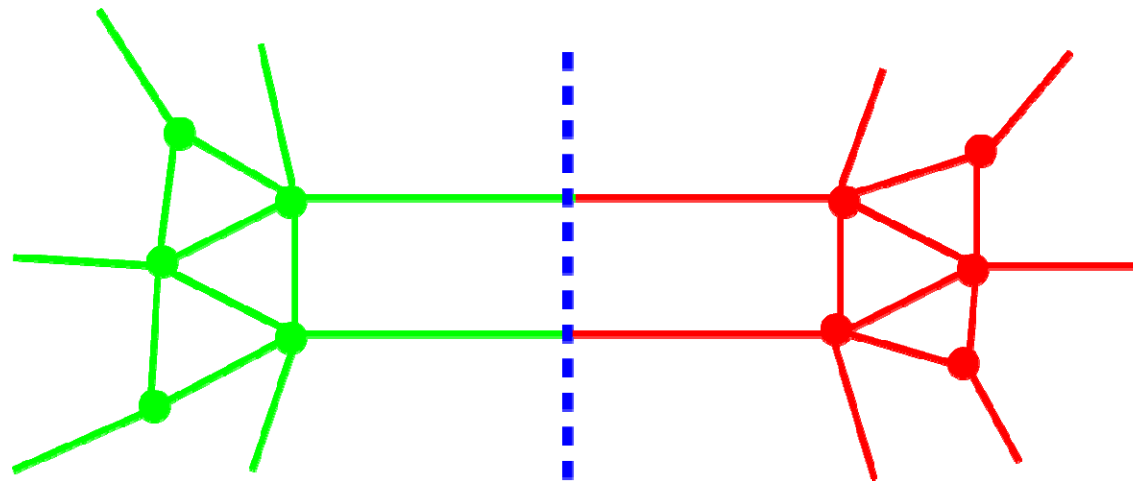


DSC Method (4): Effect of Partitioning

Graph partitioning: ParMETIS (University of Minnesota)

Goal:

Minimize the number of edges cut
Minimize the number of interface unknowns



Undirected graph  Symmetrize the matrix structure

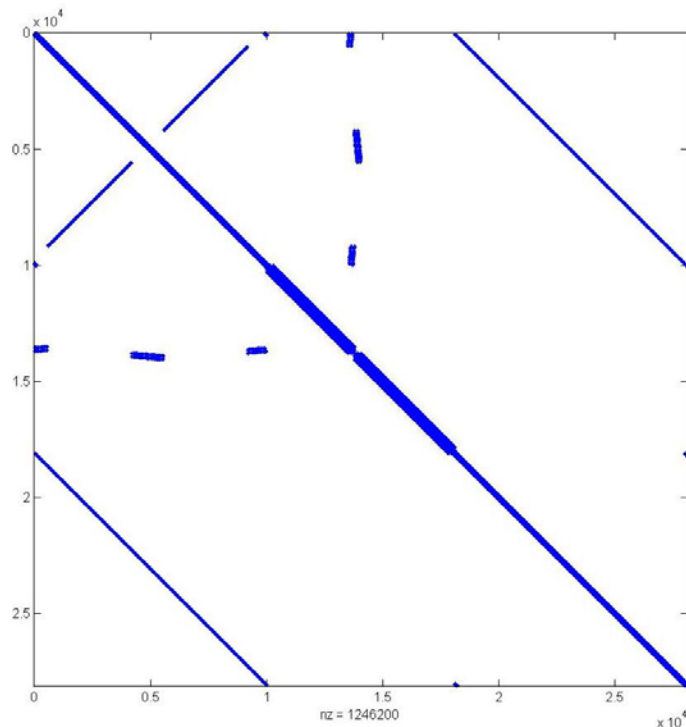
Matrix Experiments: Real or Complex Arithmetics?

Complex TRACE matrix

($n=28,120$; $nz=1,246,200$; Cond.: $6.7 \cdot 10^6$)

$$Ax = b$$

$$\Leftrightarrow (C + iD)(y + iz) = c + id$$

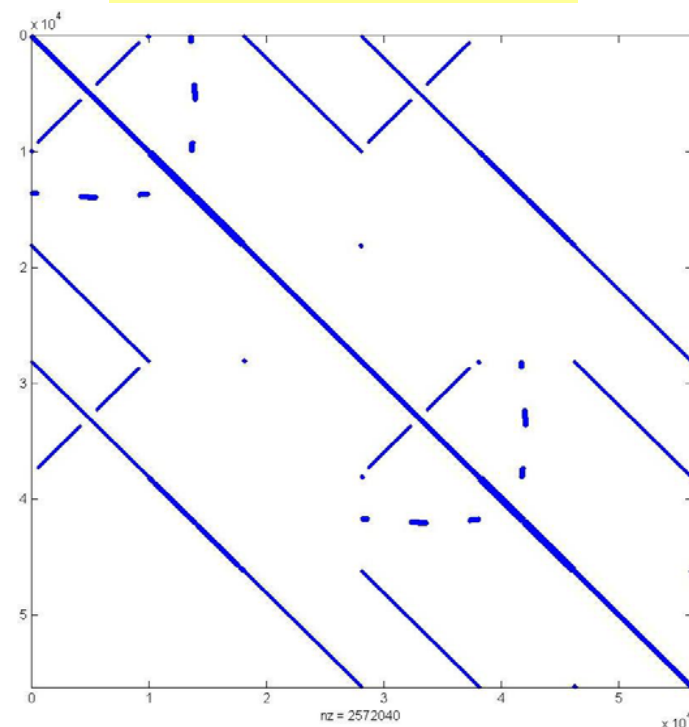


Real TRACE matrix

($n=56,240$; $nz=2,572,040$; Cond.: $8.4 \cdot 10^6$)

$$\begin{pmatrix} C & -D \\ D & C \end{pmatrix} \begin{pmatrix} y \\ z \end{pmatrix} = \begin{pmatrix} c \\ d \end{pmatrix}$$

$$\Leftrightarrow Gw = e$$

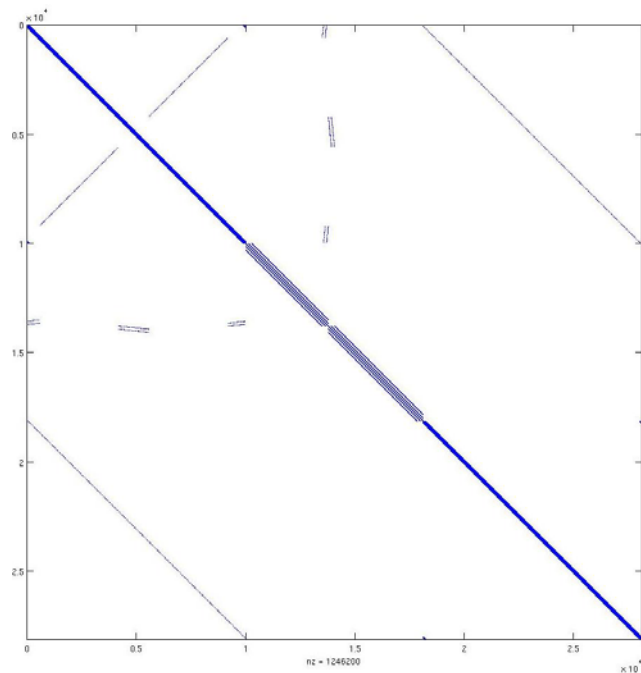




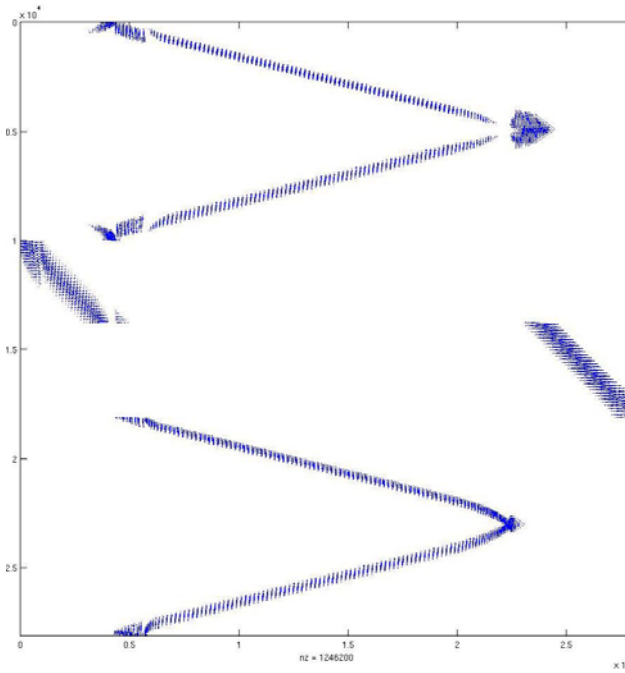
DSC Preconditioner: Matrix Permutation (complex)

Background: Fill-in reduction for ILUT preconditioning

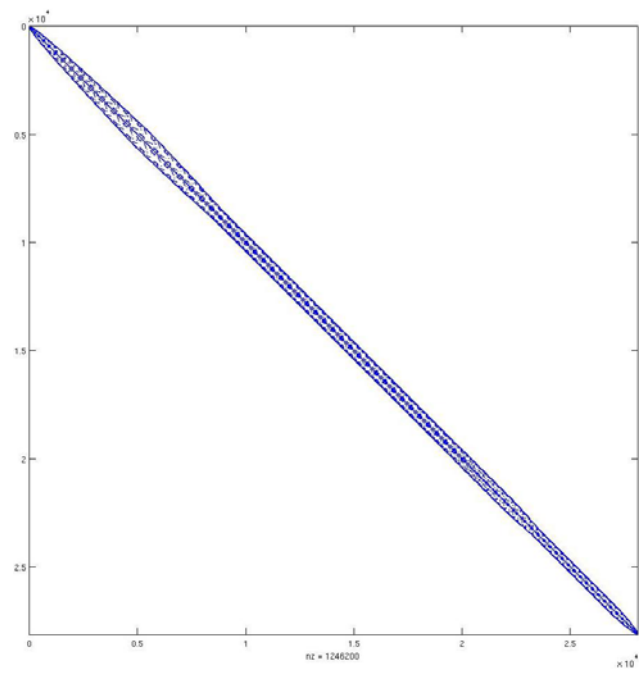
Original



Minimum Degree (MD)



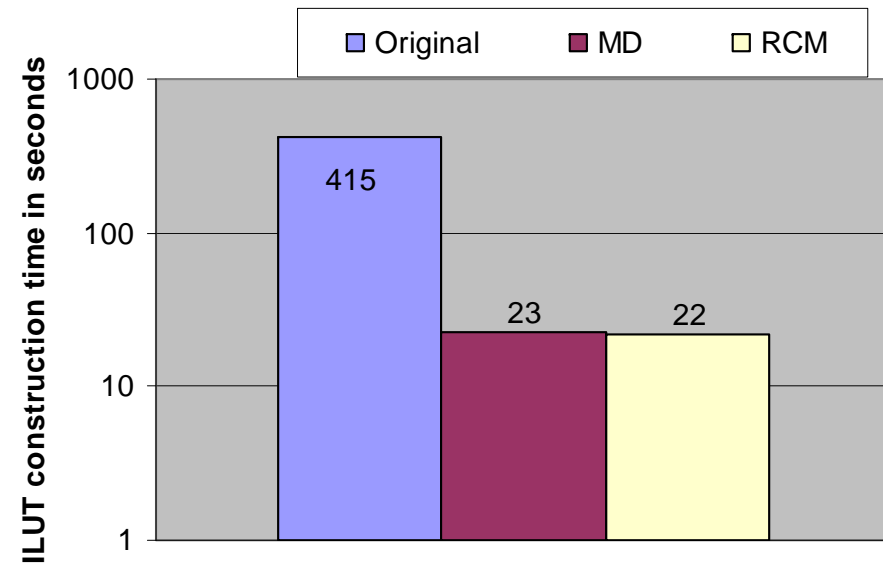
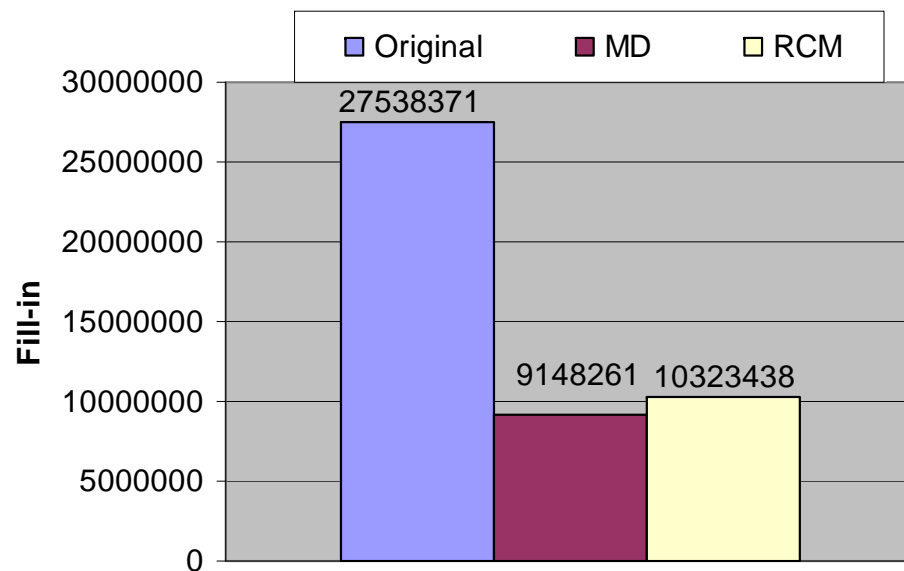
Reverse Cuthill-McKee (RCM)





ILU Preconditioner: Fill-in in L and U (complex)

MATLAB: ILUT preconditioner; threshold = 10^{-3}





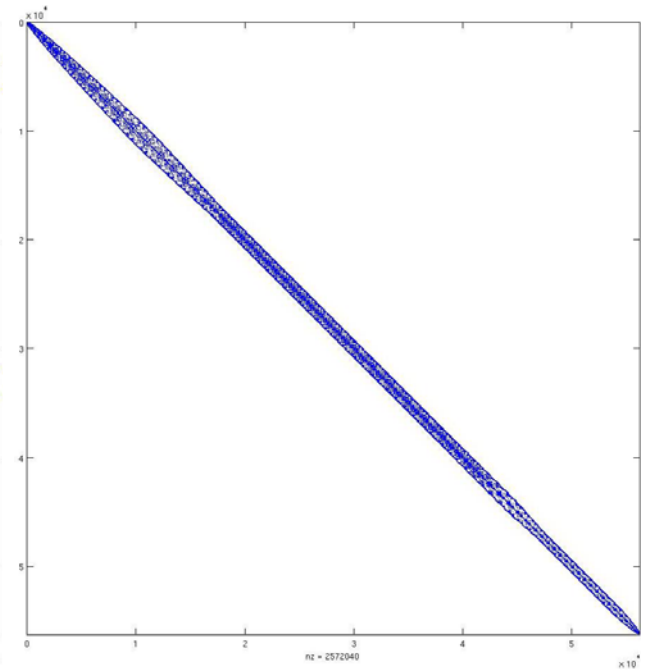
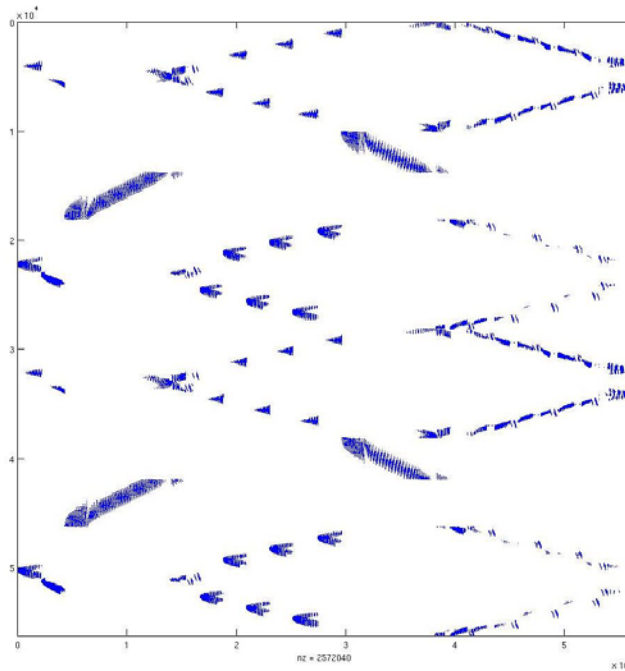
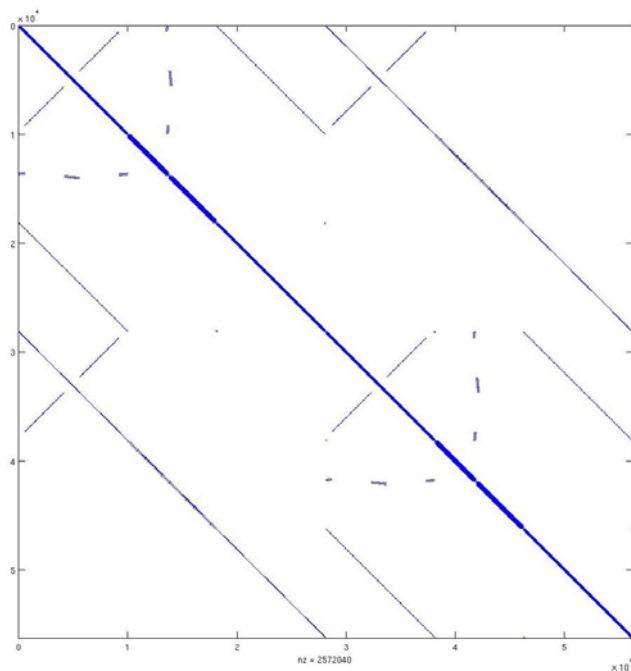
ILU Preconditioner: Matrix Permutation (real)

Background: Fill-in reduction for ILUT preconditioning

Original

Minimum Degree (MD)

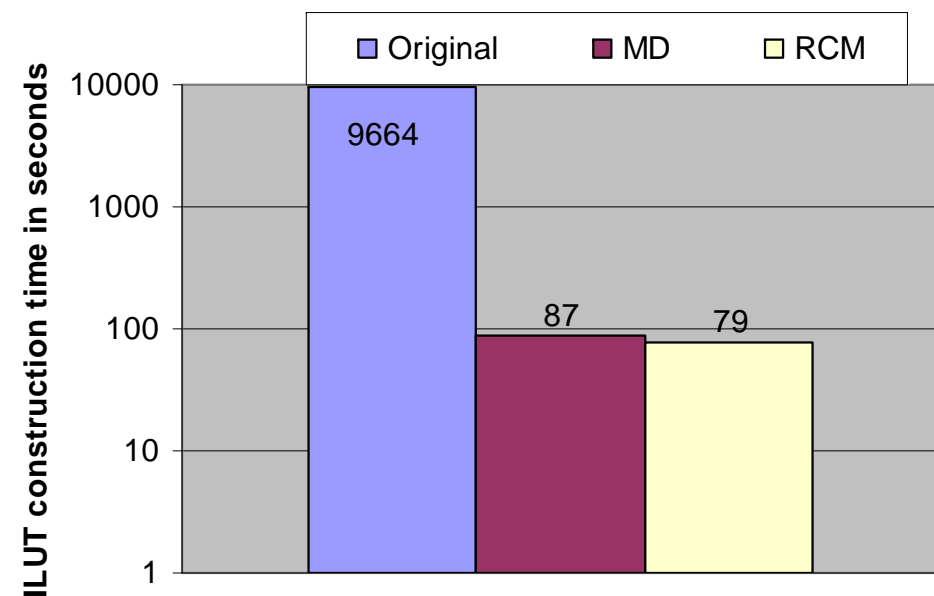
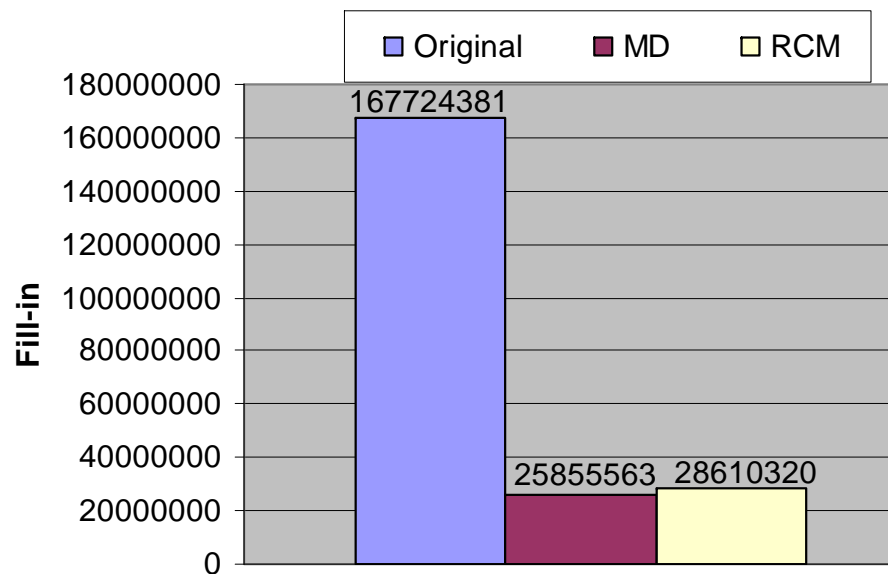
Reverse Cuthill-McKee (RCM)





ILU Preconditioner: Fill-in in L and U (real)

MATLAB: ILUT preconditioner; threshold = 10^{-3}

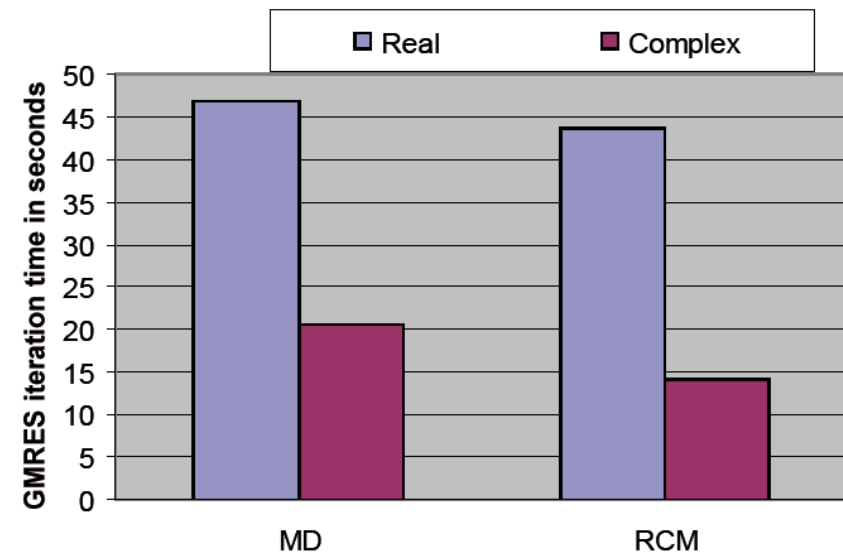
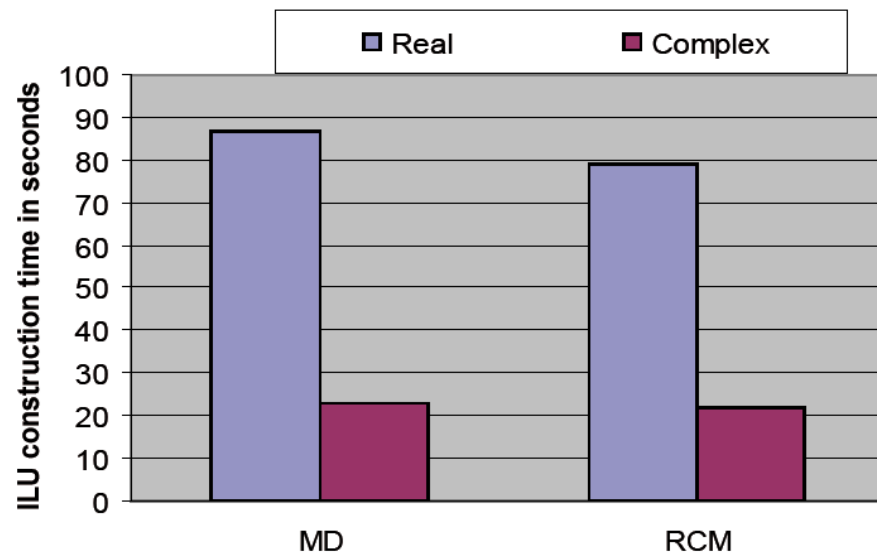




Performance: Complex or real Arithmetics?

MATLAB: ILUT preconditioning;

threshold = 10^{-3} ; |rel. residual| $< 10^{-10}$

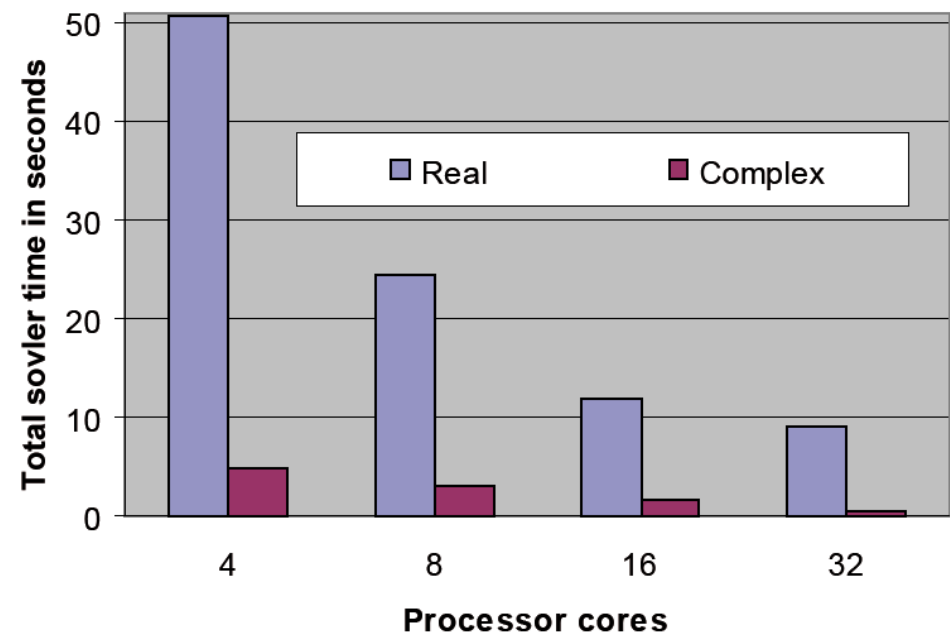
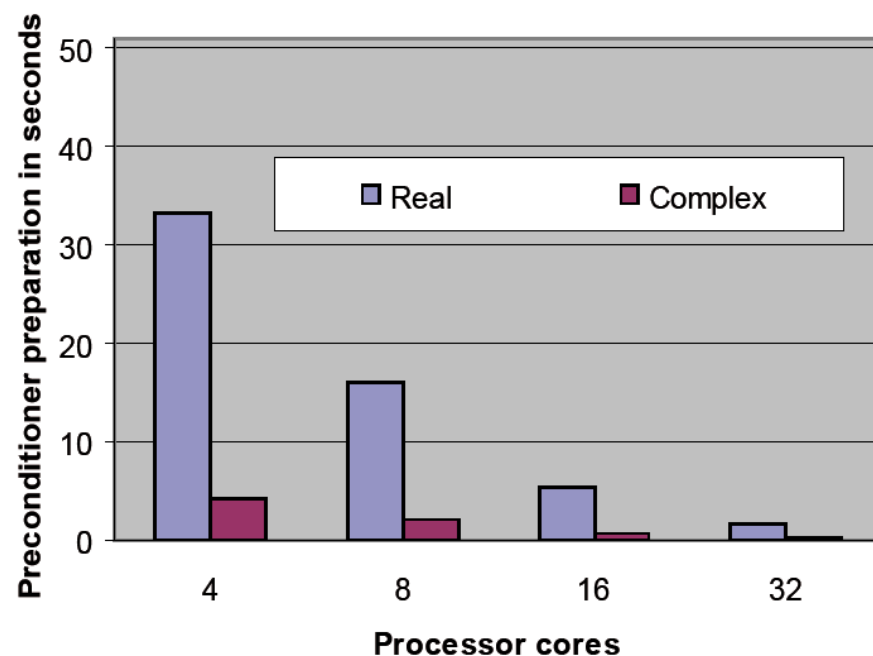




Performance on the AeroGrid Cluster of DLR

(Dual-processor nodes; Quad-Core Intel Harpertown; 2.83 GHz)

DSC method, real versus complex problem formulation

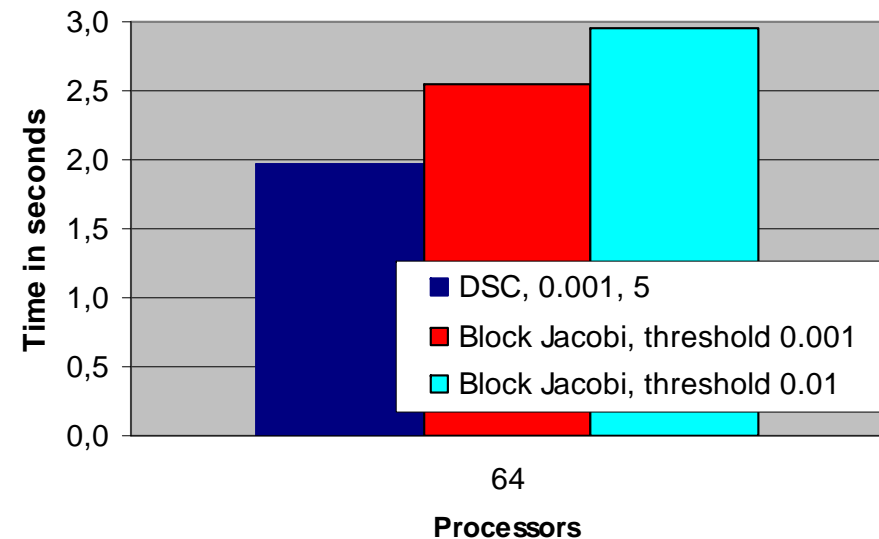
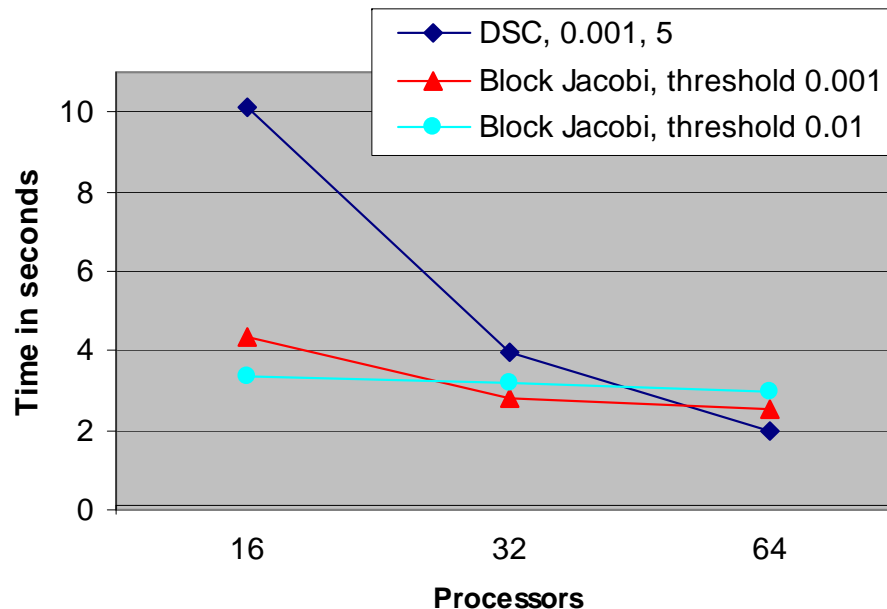




DSC Method: Performance (real)

(Dual-processor nodes; AMD Opteron 250; 2.4 GHz)

DSC method versus Block-Jacobi preconditioning (with RCM)



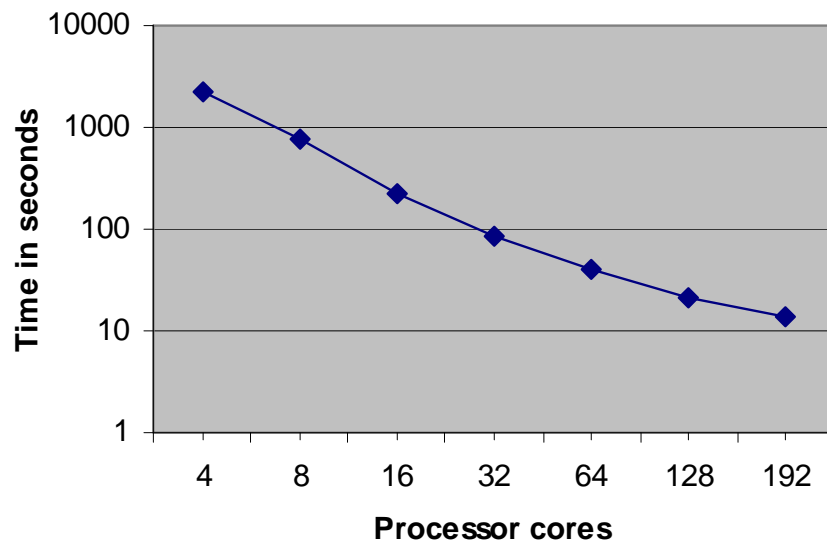
For a high processor count,
the DSC method appears to pay off.



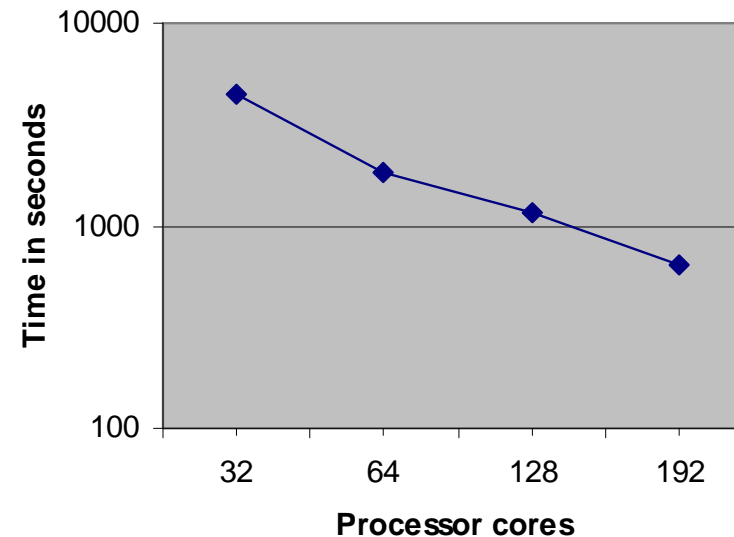


DSC Method: Strong Scaling (complex)

(Dual-processor nodes; Quad-Core Intel Harpertown; 2.83 GHz)



TRACE matrix THD
($n=378,400$; $nz=45,456,500$;
threshold = 10^{-3} ; |rel. residual| < 10^{-5})



TRACE matrix UHBR
($n=4,497,520$; $nz=552,324,700$;
threshold = 10^{-3} ; |rel. residual| < 10^{-10})



Conclusions

- **Permutation (MD, RCM) crucial for ILUT performance; slight advantages for RCM (higher locality)**
- **Complex computations significantly faster than real ones (higher locality, better ratio of calculation to memory access)**
- **DSC method lets expect higher scalability than block-local methods.**
- **Future work**
 - **Development of an intelligent solver for TRACE with problem- and convergent-dependent parameter control and preconditioning**
 - **Application of the DSC method as robust smoother in Multigrid methods**

Questions?

